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Computer Architecture Independent Adaptive Geometric Multigrid Solver for AMR-PIC

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- Motivation
- Adaptive Geometric Multigrid
- Benchmarks
- Conclusion

Goal: Understand Halo Creation and Evolution

- Halo particles become losses
 - \Rightarrow machine activation
 - \Rightarrow machine intensity limitation
- Large scale *N*-body problems of $\mathcal{O}(10^9...10^{10})$ particles coupled with Maxwell's equations
- Particle-In-Cell (PIC) models fine mesh of O(10⁸...10⁹) grid points





- Naive Meshing: Cartesian Uniform
 - Waste of memory in regions of void
 - Waste of computational power





Towards Exascale Computing

- Naive Meshing: Cartesian Uniform
 - Waste of memory in regions of void
 - Waste of computational power
- Adaptive Meshing:
 - Save memory
 - Save computational effort
 - Used in CFD, astrophysics, etc.
- Issue of state-of-the-art solvers:

Implementation is hardware specific (e.g. CPU, GPU)





- **OPAL:** physics (https://gitlab.psi.ch/OPAL/src/wikis/home)
- AMReX: grids, formerly: BoxLib (https://ccse.lbl.gov/AMReX)
- **Trilinos:** Amesos2, Belos, Ifpack2, MueLu, Tpetra (https://trilinos.org/)



Taken from https://www.cscs.ch/computers/piz-daint/



• Coordinate space discretized by grid







- Coordinate space discretized by grid
- Mark cell for refinement according to some criteria:
 - charge density per cell
 - potential gradient
 - potential magnitude
 - etc.





• Generate level 1





- Generate level 1
- Mark cell for refinement according to some criteria:
 - charge density per cell
 - potential gradient
 - potential magnitude
 - etc.





• Generate level 2





- Generate level 2
- Maximum level reached (user-defined)





Dan F. Martin and Keith L. Cartwright. Solving poisson's equation using adaptive mesh refinement. Technical Report UCB/ERL M96/66, Univ. Calif. Berkeley. 1996.

• Poisson's equation:

$$\Delta \phi(x, y, z) = -rac{
ho}{arepsilon_0} \ \phi(\infty) = 0$$

with charge density ρ , vacuum permittivity ε_0 and potential ϕ .

- **Difficulty:** Continuity conservation of ϕ !
- Solution: elliptic matching condition, i.e.
 Dirichlet + Neumann condition at coarse-fine interfaces





- Implemented fully in Trilinos with **2nd generation packages**, i.e.
 - Tpetra (matrix / vector data structure)
 - Ifpack2 (smoothers e.g. Gauss-Seidel, Jacobi)
 - MueLu, Amesos2, Belos (linear solvers)



• Implemented fully in Trilinos with **2nd generation packages**, i.e.

- Tpetra (matrix / vector data structure) \rightarrow Kokkos
- Ifpack2 (smoothers e.g. Gauss-Seidel, Jacobi)
- MueLu, Amesos2, Belos (linear solvers)
- Kokkos allows **portable code** between hardware architectures **without changing your code**!
 - GPU
 - OpenMP / PThreads / serial



• 8 CRS-matrices

(prolongation, restriction, (composite) Poisson, boundaries, ...)

• 4 vectors

(RHS, LHS, residual, error)

• **Restriction:** simple averaging (N = 4 in 2D, N = 8 in 3D)



• Prolongation: Trilinear interp. or piecewise const. interp







$$\begin{split} (\Delta\phi)_{i,j} &= \frac{f_{i+\frac{1}{2},j} - f_{i-\frac{1}{2},j}^{ave} + f_{i,j+\frac{1}{2}} - f_{i,j-\frac{1}{2}}}{h_c} \\ f_{i-\frac{1}{2},j}^{ave} &= \frac{1}{2} \left(f_{top} + f_{bottom} \right), \\ f_{i+\frac{1}{2},j} &= \frac{1}{h_c} \left(\phi_{i+1,j} - \phi_{i,j} \right), \\ f_{i,j+\frac{1}{2}} &= \frac{1}{h_c} \left(\phi_{i,j+1} - \phi_{i,j} \right), \\ f_{i,j-\frac{1}{2}} &= \frac{1}{h_c} \left(\phi_{i,j} - \phi_{i,j-1} \right) \end{split}$$

$$f_{top/bottom} = \frac{1}{h_f} \left(\phi_{top/bottom}^{int} - \phi_{top/bottom} \right)$$





$$\begin{split} (\Delta\phi)_{i,j} &= \frac{f_{i+\frac{1}{2},j} - f_{i-\frac{1}{2},j}^{ave} + f_{i,j+\frac{1}{2}} - f_{i,j-\frac{1}{2}}}{h_c} \\ f_{i-\frac{1}{2},j}^{ave} &= \frac{1}{2} \left(f_{top} + f_{bottom} \right), \\ f_{i+\frac{1}{2},j} &= \frac{1}{h_c} \left(\phi_{i+1,j} - \phi_{i,j} \right), \\ f_{i,j+\frac{1}{2}} &= \frac{1}{h_c} \left(\phi_{i,j+1} - \phi_{i,j} \right), \\ f_{i,j-\frac{1}{2}} &= \frac{1}{h_c} \left(\phi_{i,j} - \phi_{i,j-1} \right) \end{split}$$

$$f_{top/bottom} = \frac{1}{h_f} \left(\phi_{top/bottom}^{int} - \phi_{top/bottom} \right)$$

 \implies Lagrange interpolation



•

$$g(u,v) = \sum_{i,j=0}^{2} f(u_i,v_j)L_i(u)L_j(v)$$

with

$$L_{i}(x) = \frac{(x - x_{k})(x - x_{l})}{(x_{i} - x_{k})(x_{i} - x_{l})} \qquad (l \neq i \neq k \neq l)$$

Cells need to be uncovered! \implies 9 possible configurations







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M. J. Turk, B. D. Smith, J. S. Oishi, S. Skory, S. W. Skillman, T. Abel, M. L. Norman, yt: A Multi-code Analysis Toolkit for Astrophysical Simulation Data, Astrophysical Journal, Supplement 192 (2011) 9.

22 / 28

Benchmark - Lineplots AMReX FMG vs. AGMG





- 10 bunches (each $\approx 3 \cdot 10^8$ particles)
- base grid: 576³
- max. grid: 24

 $(\rightarrow$ max. 13'824 cores on base level)

- #level of refinement: 2
- 100 solves

(move each particle randomly within [-0.001, 0.001] after every solve)





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Solver ...

- works and gives good scalability (CPUs)
- runs on GPUs (EuroHack18: GPU Programming Hackathon)
- is hardware architecture independent
- is part of open-source beam dynamics code OPAL
- uses **structured aggregation** for bottom level linear system of equations solve (Sandia visit: 15th 19th Oct. 2018)



Wir schaffen Wissen - heute für morgen

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