High-Precision Lossy Eigenfield Analysis Based on the Finite Element Method



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- TESLA Type Cavities (1.3 GHz and 3.9 GHz)
 - Photograph 1.3 GHz



- Numerical model 1.3 GHz

http://newsline.linearcollider.org



CST Studio Suite 2018



















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Motivation

Modeling of detailed structures



TESLA 3.9 GHz structure







• HOM coupler

Modeling of entire modules

Motivation

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Bellow



Boundary conditions







- TESLA 3.9 GHz Cavity
 - CAD Model of the Vacuum with surface mesh on the PEC couplers







Port boundary condition







Port boundary condition





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Computational Model

- Problem formulation
 - Local Ritz approach

$$\vec{E} = \vec{E}(\vec{r})$$
$$= \sum_{i=1}^{n} \alpha_i \, \vec{w}_i(\vec{r})$$

- $ec{w}$ vectorial function
- α_i scalar coefficient
- i global index
- n number of DOFs







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- Problem formulation
 - Local Ritz approach

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- \vec{w} vectorial function
- α_i scalar coefficient
- i global index
- n number of DOFs

$$\begin{aligned} \operatorname{curl} 1/\mu_{\Gamma} \operatorname{curl} \vec{E} &= \left(\frac{\omega}{c_{0}}\right)^{2} \varepsilon_{\Gamma} \vec{E} \Big|_{\vec{r} \in \Omega} \\ \operatorname{div}(\varepsilon \vec{E}) \Big| &= 0 \\ \vec{r} \in \Omega \end{aligned} + \text{boundary conditions} \end{aligned}$$

continuous eigenvalue problem, loss-free

$$A_{ij} = \iint_A 1/\mu_{
m r} \operatorname{curl} \vec{w_i} \cdot \operatorname{curl} \vec{w_j} \, \mathrm{d}\Omega$$

 $B_{ij} = \iint_A \varepsilon_{
m r} \, \vec{w_i} \cdot \vec{w_j} \, \mathrm{d}\Omega$

$$ec{w}_i(x,y,z) = ec{w}_i(x,y) \cdot e^{-ik_z z}$$

$$A\vec{\alpha} = (\frac{\omega}{c_0})^2 B\vec{\alpha}$$

discrete eigenvalue problem





eigenvector and

eigenvalue

Problem formulation

- Determine propagation constant for a fixed frequency

$$\begin{pmatrix} A_{11} & 0\\ 0 & 0 \end{pmatrix} \begin{pmatrix} \vec{y}_t\\ \vec{y}_z \end{pmatrix} = -k_z^2 \begin{pmatrix} B_{11} & B_{12}\\ B_{21} & B_{22} \end{pmatrix} \begin{pmatrix} \vec{y}_t\\ \vec{y}_z \end{pmatrix}$$

algebraic eigenvalue problem







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- Problem formulation
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$$ec{E} = ec{E}(ec{r})$$
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continuous eigenvalue problem

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$$A_{ij} = \iiint_{\Omega} 1/\mu_{r} \operatorname{curl} \vec{w}_{i} \cdot \operatorname{curl} \vec{w}_{j} \, \mathrm{d}\Omega$$

 $B_{ij} = \iiint_{\Omega} \varepsilon_{r} \, \vec{w}_{i} \cdot \vec{w}_{j} \, \mathrm{d}\Omega$
 $C_{ij} = \iiint_{\Omega} Z_{0} \sigma \, \vec{w}_{i} \cdot \vec{w}_{j} \, \mathrm{d}\Omega$

$$A\vec{\alpha} + j\frac{\omega}{c_0}C\vec{\alpha} + (j\frac{\omega}{c_0})^2 B\vec{\alpha} = 0$$

discrete eigenvalue problem





Jacobi-Davidson method

- Important properties
 - Direct solution difficult because of dense matrix in correction equation.
 - Iterative solution not immediately applicable because vectors $\Delta \vec{x}$ with $\Delta \vec{x} \in R\{(V_B)_{\perp}\}$ are not mapped back onto $R\{(V_B)_{\perp}\}$ again.
- Preconditioning
 - The JD preconditioner

 $PC = \{I - M^{-1}V_B[(M^{-1}V_B)^T V_B]^{-1}V_B^T\}M^{-1}$ = $M^{-1} - M^{-1}V_B[(M^{-1}V_B)^T V_B]^{-1}V_B^T M^{-1}$

retains the property $\Delta \vec{x} \in R\{(V_B)_{\perp}\}$ for any preconditioner M^{-1} .

Simplest case:
$$M^{-1} = I \quad \hookrightarrow \quad PC = I - VV_B^T = P$$





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- Controlling the Jacobi-Davidson eigenvalue solver
 - Evaluation in the complex frequency plane
 - Select best suited eigenvalues in circular region around user-specified complex target





Quality factor versus frequency







- Lossless accelerator cavity
 - Eigenvalues on the real axis



- choose an initial guess
- expand the search space ...
- until an approximate solution is found
- the solution becomes the new initial guess
- continue expanding the search space ...





- Lossy accelerator cavity
 - Eigenvalues in the complex plane



- choose an initial guess
- expand the search space ...
- until an approximate solution is found
- choose another initial guess
- continue expanding the search space ...
- find another approximate solution
- if we choose an unsuitable initial guess
- the algorithm will converge to ...
- an already determined eigenvalue!!!





Accurate computation of eigenpairs inside a region enclosed by a non-self-intersecting curve



- choose a region to look for eigenvalues
- the region can be of any shape, e.g rectangle ...
- circle/ellipse
- most computation is spent to solve linear equation systems at different interpolation points which can be parallelized.







▼×



- TESLA 3.9 GHz Cavity
 - Fundamental mode

Absolute value of the electric field strength

$|\vec{E}|$

Logarithmic scale from 1e4 to 1e7 V/m

LPW = 20 3.337.736 Tetrahedrons





Convergence study for global quantities

- Resonance frequency







Convergence study for global quantities

- Quality factor









∑×













TECHNISCHE Computational Model UNIVERSITÄT DARMSTADT Port PITZ Gun - Doorknob Rectangular transition Waveguide Coaxial Waveguide Lossy Cavity Doorknob (PEC) Grid Antenna (Copper)













M. Otevrel, "Report on Gun Conditioning Activities at PITZ in 2013"























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Antenna Tuning

Parameter: Seal Thickness







- Cavity Tuning
 - Rotationally symmetric model







 $R_{half} = (89.95 + 0.234 - 0.048 + 0.012) \text{ mm} = 90.148 \text{ mm}$ Cavity Tuning $R_{full} = (90.32 + 0.172 - 0.021 + 0.002) \text{ mm} = 90.473 \text{ mm}$ $E_z / V/m$ F7 3.0×10^{7} $E_{z,half}/E_{z,full} = 1.13$ 2.5×10^{7} $E_{z,half}/E_{z,full} = 1.00$ 2.0×10^{7} f_{res}= 1302.493 MHz 1.5×10^{7} f_{res}= 1299.999 MHz 1.0×10^{7} $L_{coax} = -2.0 \text{ mm}$ 5.0 × 10⁶ 0 z/m 0.05 0.15 0.20 0.25 0.30 0.00 0.10





• Electric Field Strength $|\vec{E}| = \sqrt{\vec{E} \cdot \vec{E^*}}$







• Magnetic Flux Density $|\vec{B}| = \sqrt{\vec{B} \cdot \vec{B}^*}$







• Electric Field Strength $\vec{E}(t) = \operatorname{Re}(\vec{E} \cdot e^{i\omega t})$







• Electric Field Strength $\vec{E}(t) = \operatorname{Re}(\vec{E} \cdot e^{i\omega t})$













• Poynting Vector $\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^*$ - Active power GlyphVector Magnitude 2.0e+06 1e+7 2e+7 5e+7 1e+8 2.0e+08 5e+6 $\operatorname{Re}(\vec{S})$









Outline



Summary

- High-Precision Lossy Eigenfield Analysis based on the FEM available
- Lossy mechanism may include volume losses and surface losses due to materials as well as surface losses due to port boundary conditions
- Any number of ports and any number of modes per port are possible
- Two types of eigensolver applicable (JDM and CIM)
- Outlook
 - Merge JDM and CIM into a single code to efficiently take advantage of both methods

