



BERKELEY LAB

Bringing Science Solutions to the World



U.S. DEPARTMENT OF
ENERGY

Parallel Algorithms for solving Nonlinear Eigenvalue Problems in Accelerator Cavity Simulations

Roel Van Beeumen

`rvanbeeumen@lbl.gov`

Computational Research Division
Lawrence Berkeley National Laboratory

Joint work with O. Marques (LBNL), E.G. Ng (LBNL), C. Yang (LBNL), Z. Bai (UC Davis),
L. Ge (SLAC), O. Kononenko (SLAC), Z. Li (SLAC), C.-K. Ng (SLAC), L. Xiao (SLAC)

ICAP'18 – Key West, FL – October 23, 2018

Motivation: Nonlinear boundary conditions

Maxwell's equations

$$\nabla \times \left(\frac{1}{\mu} \nabla \times E \right) - \lambda \varepsilon E = 0$$

Motivation: Nonlinear boundary conditions

Maxwell's equations

$$\nabla \times \left(\frac{1}{\mu} \nabla \times E \right) - \lambda \varepsilon E = 0$$

E oscillating
 \implies
particular freq.

Motivation: Nonlinear boundary conditions

Maxwell's equations

$$\nabla \times \left(\frac{1}{\mu} \nabla \times E \right) - \lambda \epsilon E = 0$$

E oscillating
 \implies
particular freq.

Eigenvalue problem

- eigenvalue \rightarrow complex frequency
- eigenvector \rightarrow electric field

Motivation: Nonlinear boundary conditions

Maxwell's equations

$$\nabla \times \left(\frac{1}{\mu} \nabla \times E \right) - \lambda \epsilon E = 0$$

E oscillating
 \implies
particular freq.

Eigenvalue problem

- eigenvalue \rightarrow complex frequency
- eigenvector \rightarrow electric field

Option 1:

- closed cavity
- no volumetric losses
- no surface loss

\implies

Real symmetric **linear** eigenvalue problem

Motivation: Nonlinear boundary conditions

Maxwell's equations

$$\nabla \times \left(\frac{1}{\mu} \nabla \times E \right) - \lambda \epsilon E = 0$$

E oscillating
 \implies
particular freq.

Eigenvalue problem

- eigenvalue \rightarrow complex frequency
- eigenvector \rightarrow electric field

Option 1:

- closed cavity
- no volumetric losses
- no surface loss

\implies

Real symmetric **linear** eigenvalue problem

Option 2:

- cavity with waveguides
- to couple external power sources
- to damp high order modes

\implies

Nonlinear eigenvalue problem

Motivation: Nonlinear boundary conditions

Terminate propagation of E

→ (nonlinear) boundary conditions

Accelerator cavity nonlinear eigenvalue problem

$$\left(K - \lambda M + i\sqrt{\lambda} W^{\text{TEM}} + i \sum_m \sqrt{\lambda - \kappa_m} W_m^{\text{TE}} + i \sum_m \frac{\lambda}{\sqrt{\lambda - \kappa_m}} W_m^{\text{TM}} \right) x = 0$$

- $\lambda = k^2$
- $\kappa_m = (k_m^c)^2$ cutoff values of m th waveguide mode

1 Solving Nonlinear Eigenvalue Problems

- Approximation
- Linearization pencils
- Solving linear eigenvalue problem

2 Numerical Experiments

- Pillbox cavity
- TESLA SRF cavity cryomodule

NLEP

The nonlinear eigenvalue problem:

$$F(\lambda)x = 0$$

where

- $\lambda \in \Omega \subseteq \mathbb{C}$: eigenvalue
- $x \in \mathbb{C}^n \setminus \{0\}$: eigenvector
- $F : \Omega \rightarrow \mathbb{C}^{n \times n}$: matrix-valued function

Nonlinear eigenvalue problem (NLEP)

NLEP

The nonlinear eigenvalue problem:

$$F(\lambda)x = 0$$

where

- $\lambda \in \Omega \subseteq \mathbb{C}$: eigenvalue
- $x \in \mathbb{C}^n \setminus \{0\}$: eigenvector
- $F : \Omega \rightarrow \mathbb{C}^{n \times n}$: matrix-valued function

Note that the NLEP is

- ↪ **nonlinear** in eigenvalue λ ,
- ↪ **linear** in eigenvector x .

NLEP

The nonlinear eigenvalue problem:

$$F(\lambda)x = \left(\sum_{i=1}^k B_i f_i(\lambda) \right) x = 0$$

where

- $\lambda \in \Omega \subseteq \mathbb{C}$: eigenvalue
- $x \in \mathbb{C}^n \setminus \{0\}$: eigenvector
- $F : \Omega \rightarrow \mathbb{C}^{n \times n}$: matrix-valued function

NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

$$L(\lambda)x = 0$$



Solution

- 1 approximation via interpolation
- 2 linearization
- 3 solving linear eigenvalue problem

NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

$$L(\lambda)x = 0$$



Solution

Step 1: Polynomial interpolation

$$F(\lambda) \approx P_d(\lambda) = A_0 + A_1\lambda + A_2\lambda^2 + \cdots + A_d\lambda^d$$

NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

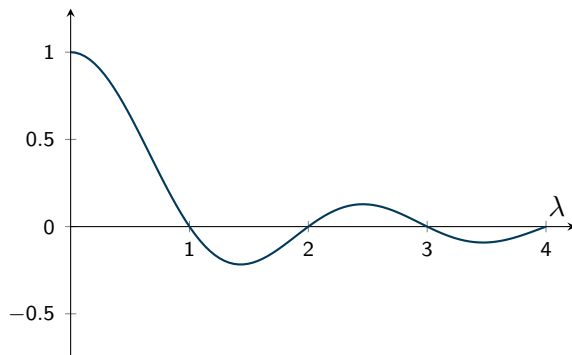
$$L(\lambda)x = 0$$



Solution

Step 1: Polynomial interpolation

$$F(\lambda) \approx P_d(\lambda) = A_0 + A_1\lambda + A_2\lambda^2 + \dots + A_d\lambda^d$$



NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

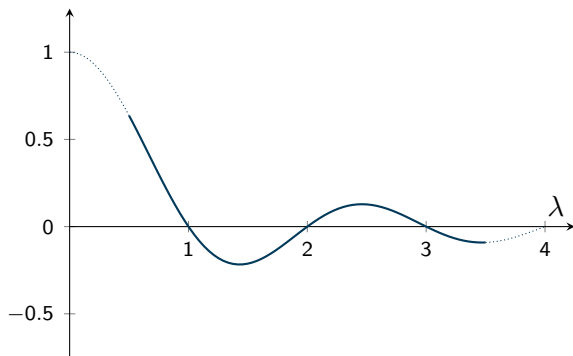
$$L(\lambda)x = 0$$



Solution

Step 1: Polynomial interpolation

$$F(\lambda) \approx P_d(\lambda) = A_0 + A_1\lambda + A_2\lambda^2 + \dots + A_d\lambda^d$$



NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

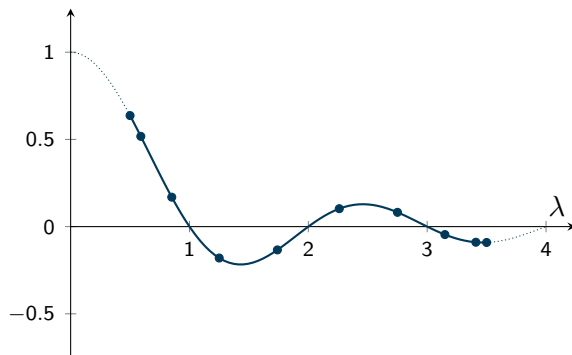
$$L(\lambda)x = 0$$



Solution

Step 1: Polynomial interpolation

$$F(\lambda) \approx P_d(\lambda) = A_0 + A_1\lambda + A_2\lambda^2 + \dots + A_d\lambda^d$$



NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

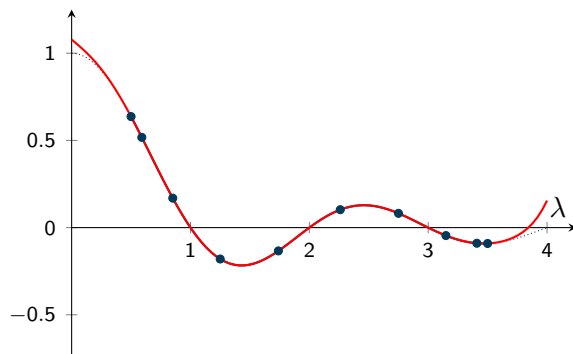
$$L(\lambda)x = 0$$



Solution

Step 1: Polynomial interpolation

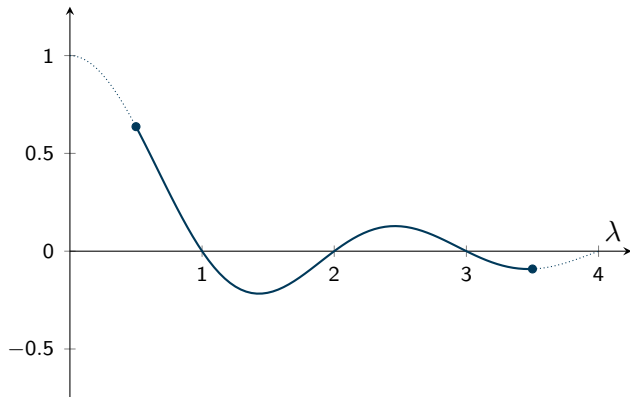
$$F(\lambda) \approx P_d(\lambda) = A_0 + A_1\lambda + A_2\lambda^2 + \dots + A_d\lambda^d$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

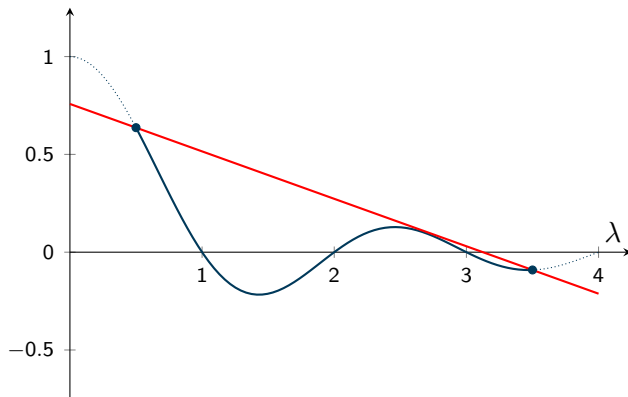
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

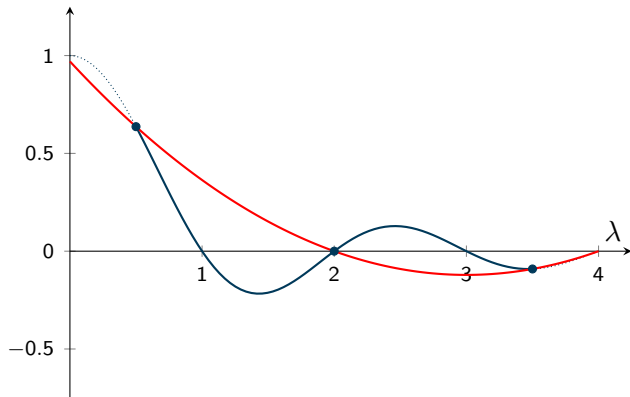
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

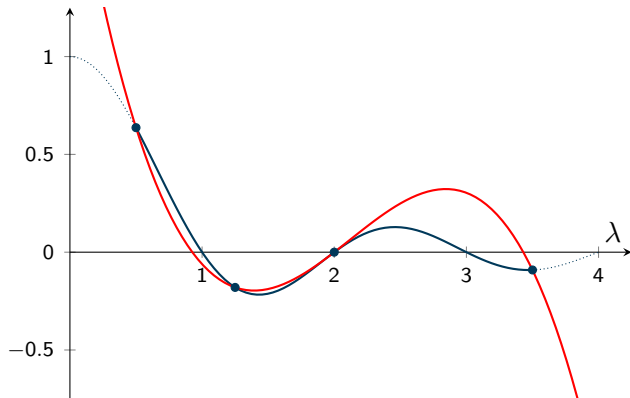
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + A_2 n_2(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

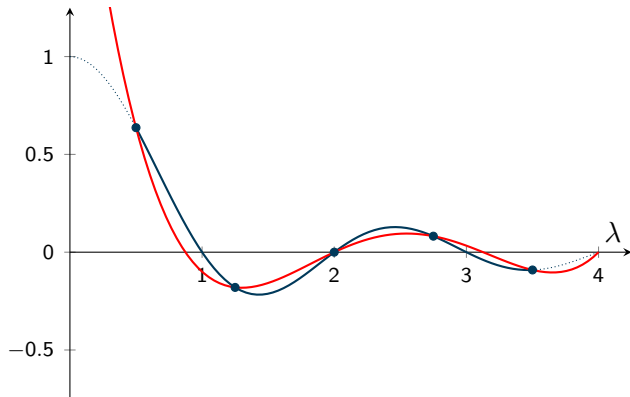
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_3 n_3(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

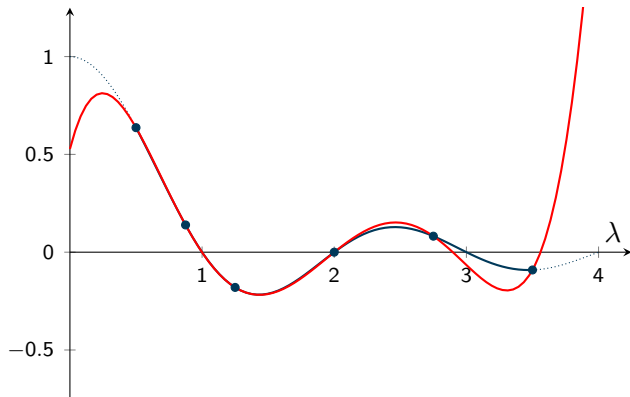
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_4 n_4(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

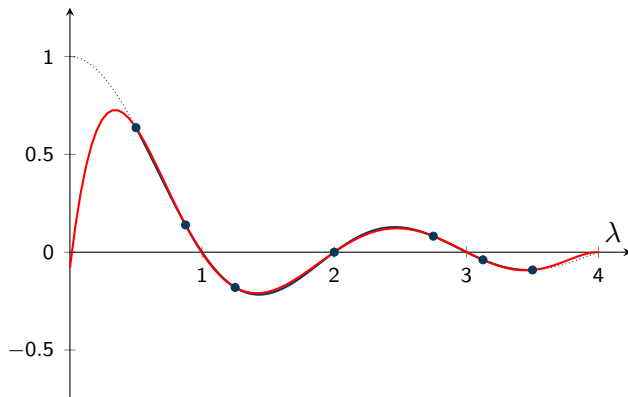
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_5 n_5(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

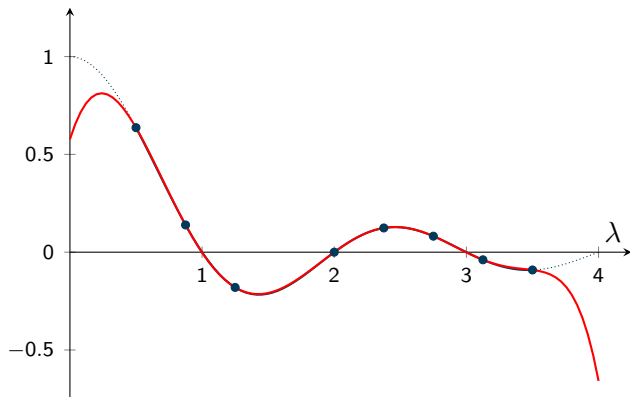
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_6 n_6(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

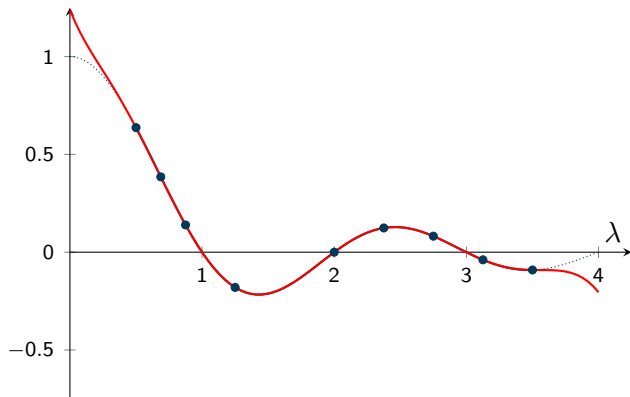
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_7 n_7(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

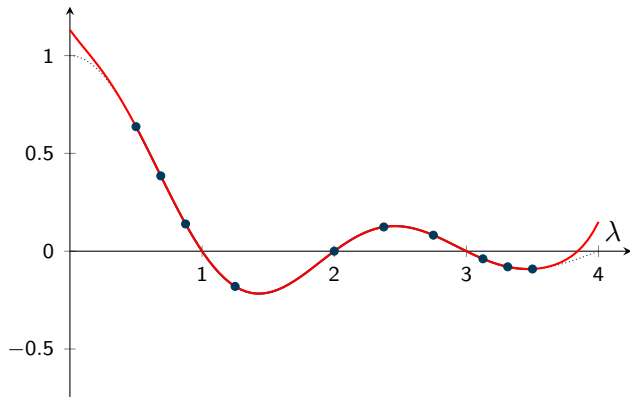
$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_8 n_8(\lambda)$$



Approximation: Newton interpolation

Dynamic polynomial interpolation (Newton)

$$F(\lambda) \approx A_0 n_0(\lambda) + A_1 n_1(\lambda) + \dots + A_9 n_9(\lambda)$$

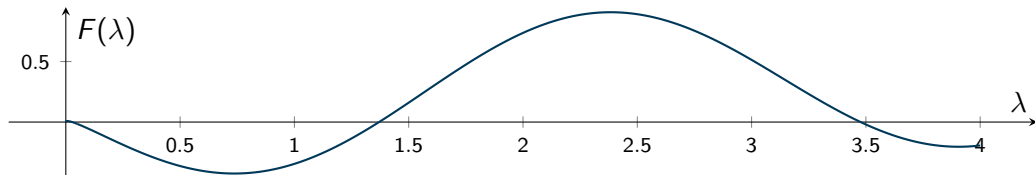


Approximation: Polynomial versus Rational

Scalar nonlinear function:

$$F(\lambda) = 0.2\sqrt{\lambda} - 0.6\sin(2\lambda) = 0$$

with target set: $\Sigma = [0.01, 4]$

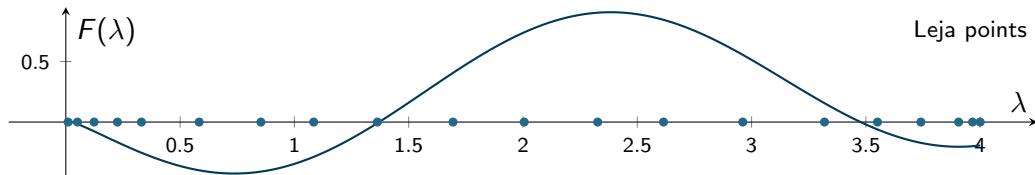


Approximation: Polynomial versus Rational

Scalar nonlinear function:

$$F(\lambda) = 0.2\sqrt{\lambda} - 0.6\sin(2\lambda) = 0$$

with target set: $\Sigma = [0.01, 4]$

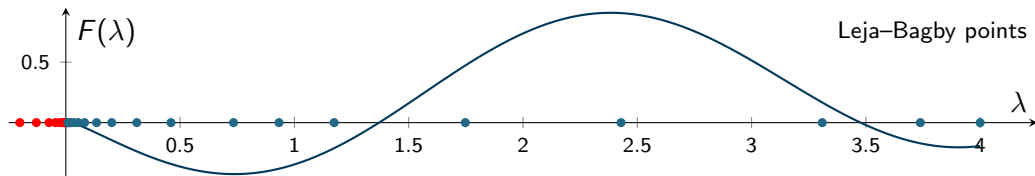
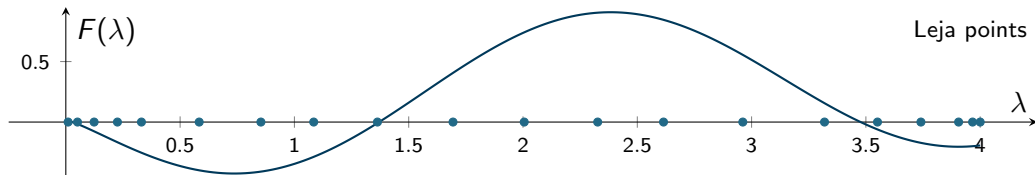


Approximation: Polynomial versus Rational

Scalar nonlinear function:

$$F(\lambda) = 0.2\sqrt{\lambda} - 0.6\sin(2\lambda) = 0$$

with target set: $\Sigma = [0.01, 4]$

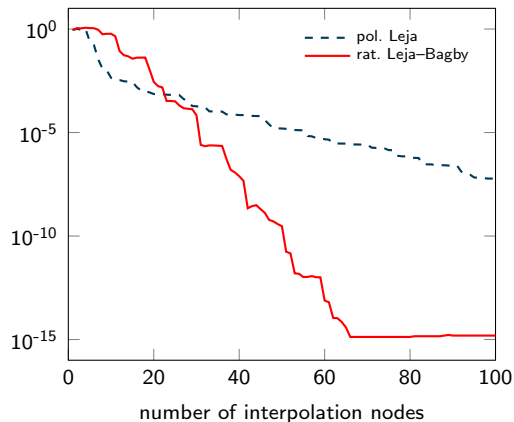


Approximation: Polynomial versus Rational

Scalar nonlinear function:

$$F(\lambda) = 0.2\sqrt{\lambda} - 0.6 \sin(2\lambda) = 0$$

interpolation error

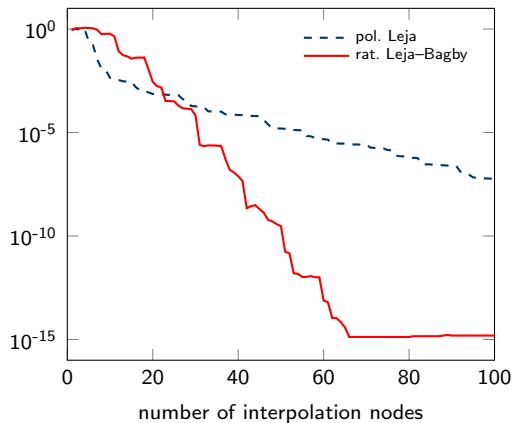


Approximation: Polynomial versus Rational

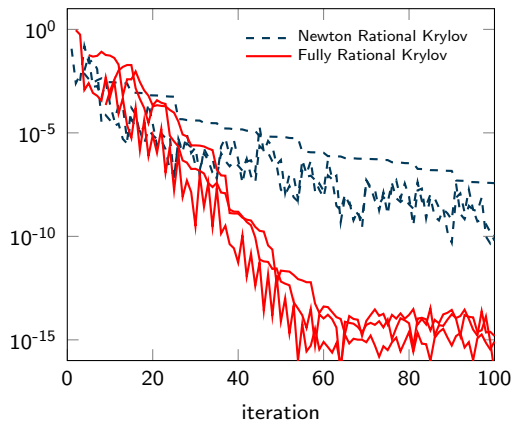
Scalar nonlinear function:

$$F(\lambda) = 0.2\sqrt{\lambda} - 0.6 \sin(2\lambda) = 0$$

interpolation error



convergence of eigenvalues



NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

$$\mathbf{L}(\lambda)\mathbf{x} = 0$$



Solution

Step 2: Linearization

$$P_d(\lambda)x = 0$$



$$\mathbf{L}(\lambda)\mathbf{x} = (\mathbf{A} - \lambda\mathbf{B})\mathbf{x} = 0$$

Linearization: idea

Second order ODE

$$M\ddot{q} + C\dot{q} + Kq = 0$$

System of first order ODEs

$$\begin{cases} \dot{q}_1 = q_2 \\ M\dot{q}_2 = -Cq_2 - Kq_1 \end{cases}$$

$$\begin{bmatrix} I & 0 \\ 0 & M \end{bmatrix} \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} 0 & I \\ -K & -C \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$

Linearization: idea

Second order ODE

$$M\ddot{q} + C\dot{q} + Kq = 0$$

System of first order ODEs

$$\begin{cases} \dot{q}_1 = q_2 \\ M\dot{q}_2 = -Cq_2 - Kq_1 \end{cases}$$

$$\begin{bmatrix} I & 0 \\ 0 & M \end{bmatrix} \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} 0 & I \\ -K & -C \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$

Quadratic eigenvalue problem

$$(M\lambda^2 + C\lambda + K)x = 0$$

Linear eigenvalue problem

$$\lambda \begin{bmatrix} I & 0 \\ 0 & M \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 & I \\ -K & -C \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Step 2: Companion linearization

PEP

$$P_d(\lambda)x = 0$$

\Rightarrow

GEP

$$\mathbf{L}(\lambda)\mathbf{x} = (\mathbf{A} - \lambda\mathbf{B})\mathbf{x} = 0$$

$$P_d(\lambda)x = \left(A_0 + A_1\lambda + A_2\lambda^2 + \cdots + A_d\lambda^d \right) x = 0$$

$$\underbrace{\begin{bmatrix} A_0 & A_1 & A_2 & \cdots & A_{d-1} \\ & I & & & \\ & & I & & \\ & & & \ddots & \\ & & & & I \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_d \end{bmatrix}}_x = \lambda \underbrace{\begin{bmatrix} 0 & 0 & \cdots & 0 & -A_d \\ I & 0 & & & \\ & \ddots & \ddots & & \\ & & I & 0 & \\ & & & I & 0 \end{bmatrix}}_{\mathbf{B}} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_d \end{bmatrix}}_x$$

$$\mathbf{L}(\lambda) = \underbrace{\left[\begin{array}{cccc} A_0 & A_1 & \cdots & A_{d-1} \\ \hline & M \otimes I_n & & \end{array} \right]}_{\mathbf{A}} - \lambda \underbrace{\left[\begin{array}{cccc} B_0 & B_1 & \cdots & B_{d-1} \\ \hline & N \otimes I_n & & \end{array} \right]}_{\mathbf{B}}$$

- Monomial basis [Mackey, Mackey, Mehl, Mehrmann 2006]
- Chebyshev basis [Effenberger, Kressner 2012]
- Lagrange basis [VB, Michiels, Meerbergen 2015]
- Newton/Hermite basis [Amiraslani, Corless, Lancaster 2009]
- Rational monomial basis [Nakatsukasa, Tisseur 2014]
- Rational Newton basis [Güttel, VB, Meerbergen, Michiels 2014]
- Spectral discretization [Jarlebring, Meerbergen, Michiels 2010]
- ...

Suppose λ is an eigenvalue of

$$L(\lambda) = \left[\begin{array}{cccc} A_0 & A_1 & \cdots & A_{d-1} \\ & & & M \otimes I_n \end{array} \right] - \lambda \left[\begin{array}{cccc} B_0 & B_1 & \cdots & B_{d-1} \\ & & & N \otimes I_n \end{array} \right]$$

with corresponding **structured eigenvector**

$$\mathbf{x} = \mathbf{a} \otimes \mathbf{x}$$

where $\mathbf{a} \in \mathbb{C}^d$.

Solving linear eigenvalue problem

NLEP

$$F(\lambda)x = 0$$



PEP

$$P_d(\lambda)x = 0$$



GEP

$$\mathbf{L}(\lambda)\mathbf{x} = 0$$

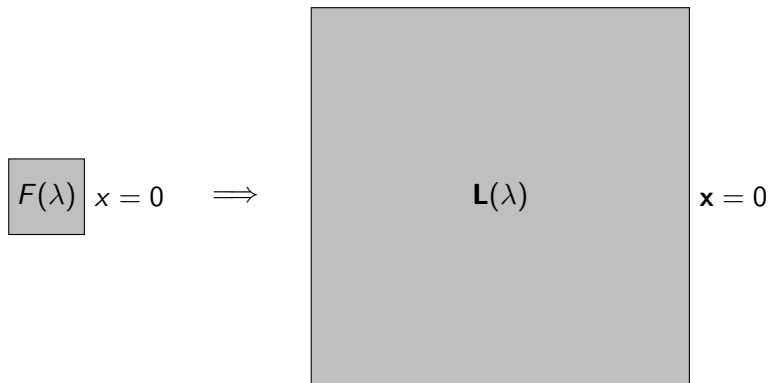


Solution

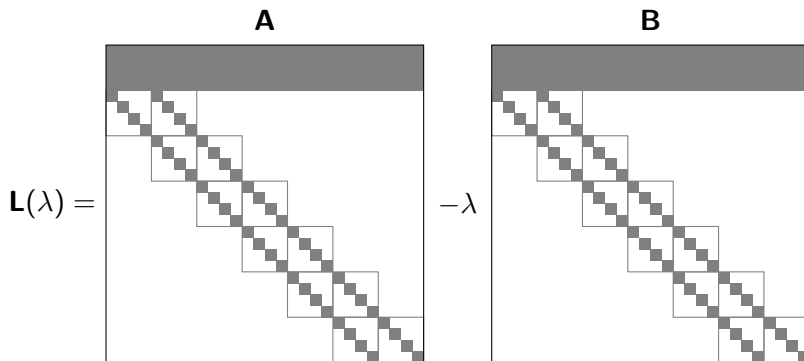
Step 3: Solve generalized linear eigenvalue problem

$$\mathbf{L}(\lambda)\mathbf{x} = (\mathbf{A} - \lambda\mathbf{B})\mathbf{x} = 0$$

by the rational Krylov method.



Compact Rational Krylov (CORK) framework



- full exploitation of structure
- reduction in memory cost
- reduction in computation cost

GEP

$$Ax = \lambda Bx$$

Arnoldi method:

- one shift σ
- shift-and-invert step:

$$w := (A - \sigma B)^{-1} Bv_j$$

- recurrence relation:

$$B^{-1}AV = V\underline{H}$$

GEP

$$Ax = \lambda Bx$$

Arnoldi method:

- one shift σ
- shift-and-invert step:

$$w := (A - \sigma B)^{-1} Bv_j$$

- recurrence relation:

$$B^{-1}AV = V\underline{H}$$

Rational Krylov method [Ruhe 1984]:

- multiple shifts $\sigma_1, \sigma_2, \dots$
- shift-and-invert step:

$$w := (A - \sigma_j B)^{-1} Bv_j$$

- recurrence relation:

$$AV\underline{H} = B\underline{V}\underline{K}$$

Compact Rational Krylov (CORK) method

Rational Krylov method with:

- 1 linearization matrices **A** and **B**

$$\left[\begin{array}{cccc} A_0 & A_1 & \cdots & A_{d-1} \\ \hline & M \otimes I_n & & \end{array} \right], \quad \left[\begin{array}{cccc} B_0 & B_1 & \cdots & B_{d-1} \\ \hline & N \otimes I_n & & \end{array} \right].$$

- 2 compact representation of subspace

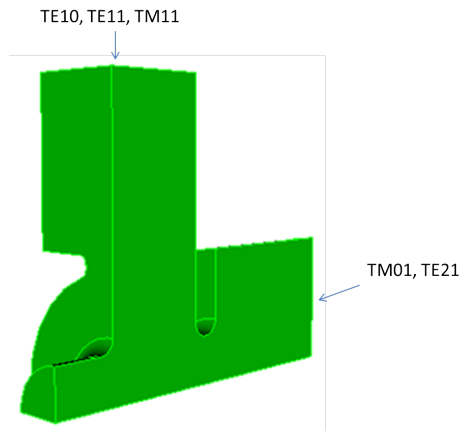
$$\mathbf{V} = (I_d \otimes Q)\mathbf{U}.$$

Simplified RF gun cavity (LCLS)

Nonlinear eigenvalue problem

$$F(\lambda)x = 0$$

target frequency window [1.0 GHz, 2.2 GHz]



Simplified RF gun cavity (LCLS)

Nonlinear eigenvalue problem

$$F(\lambda)x = 0$$

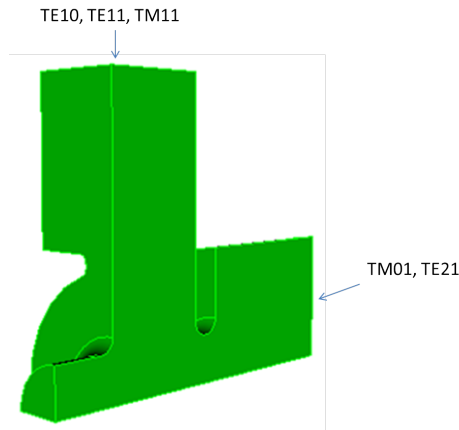
where

$$\begin{aligned} F(\lambda) = & K - \lambda M + i\sqrt{\lambda - \kappa_1} W_{10}^{\text{TE}} \\ & + i\frac{\lambda}{\sqrt{\lambda - \kappa_2}} W_{01}^{\text{TM}} + i\sqrt{\lambda - \kappa_3} W_{21}^{\text{TE}} \\ & + i\sqrt{\lambda - \kappa_4} W_{11}^{\text{TE}} + i\frac{\lambda}{\sqrt{\lambda - \kappa_4}} W_{11}^{\text{TM}} \end{aligned}$$

and

$$\begin{aligned} f_1^c &= 0.908 \text{ GHz} & f_2^c &= 1.043 \text{ GHz} \\ f_3^c &= 1.325 \text{ GHz} & f_4^c &= 1.897 \text{ GHz} \end{aligned}$$

target frequency window [1.0 GHz, 2.2 GHz]



Simplified RF gun cavity (LCLS)

$$\left(K - \lambda M + i\sqrt{\lambda - \kappa_1} W_{10}^{\text{TE}} + i\frac{\lambda}{\sqrt{\lambda - \kappa_2}} W_{01}^{\text{TM}} + i\sqrt{\lambda - \kappa_3} W_{21}^{\text{TE}} + i\sqrt{\lambda - \kappa_4} W_{11}^{\text{TE}} + i\frac{\lambda}{\sqrt{\lambda - \kappa_4}} W_{11}^{\text{TM}} \right) \mathbf{x} = 0$$

Problem parameters:

- adaptive unstructured mesh with 27,384 quadratic tetrahedral elements
- second order basis functions
- total degrees of freedom $n = 170,562$

Simplified RF gun cavity (LCLS)

$$\left(K - \lambda M + i\sqrt{\lambda - \kappa_1} W_{10}^{\text{TE}} + i\frac{\lambda}{\sqrt{\lambda - \kappa_2}} W_{01}^{\text{TM}} + i\sqrt{\lambda - \kappa_3} W_{21}^{\text{TE}} + i\sqrt{\lambda - \kappa_4} W_{11}^{\text{TE}} + i\frac{\lambda}{\sqrt{\lambda - \kappa_4}} W_{11}^{\text{TM}} \right) \mathbf{x} = 0$$

Problem parameters:

- adaptive unstructured mesh with 27,384 quadratic tetrahedral elements
- second order basis functions
- total degrees of freedom $n = 170,562$

Solution:

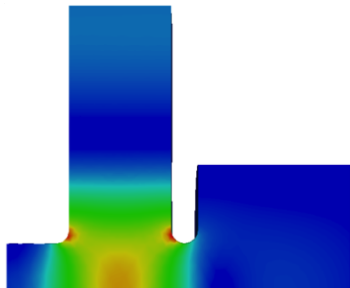
- 64 cores on NERSC Cori
- less than 3 minutes for all resonant modes in [1.0 GHz, 2.2 GHz]

Simplified RF gun cavity (LCLS)

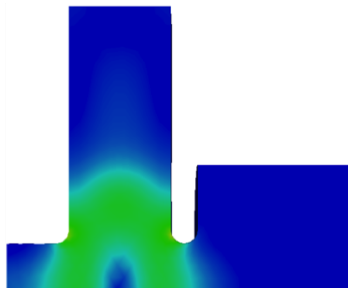
Eigenvalue λ :

- resonant mode frequency: $\text{Re}(\lambda)$
- damping factor $Q = \frac{1}{2} \frac{\text{Re}(\lambda)}{\text{Im}(\lambda)}$

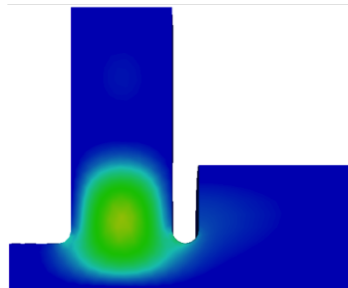
$$f_1 = 1.1762 \text{ GHz}$$
$$Q_1 = 271$$



$$f_2 = 1.1762 \text{ GHz}$$
$$Q_2 = 739$$



$$f_3 = 1.1762 \text{ GHz}$$
$$Q_3 = 693$$



Omega3P (CORK) vs S3P

Omega3P (CORK)

Solving NLEP directly

S3P

1. response calculations
2. Lorentzian fitting

Omega3P (CORK) vs S3P

Omega3P (CORK)

Solving NLEP directly

S3P

1. response calculations
2. Lorentzian fitting

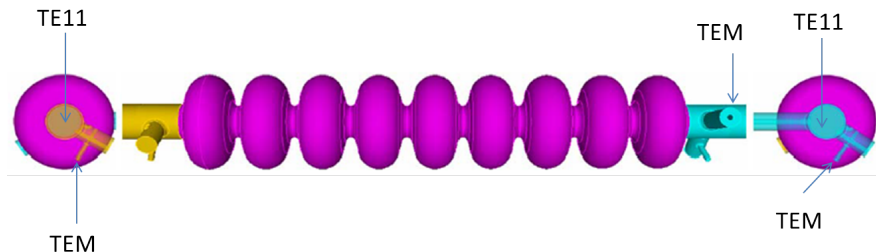
Mode	Omega3P (CORK)			S3P	
	f [GHz]	Q	rel. error	f [GHz]	Q
1	1.1762	271	1.2827e-14	1.1762	270
2	2.0567	739	2.1098e-14	2.0567	760
3	2.1960	693	4.5892e-15	2.1965	780

TESLA SRF cavity cryomodule (LCLS-II)

LCLS-II cryomodule consisting of 8 TESLA cavities

$$\left(K - \lambda M + i\sqrt{\lambda} W^{\text{TEM}} + i\sqrt{\lambda - \kappa} W_{11}^{\text{TE}} \right) x = 0$$

where $\kappa = (2\pi f_c/c)^2$ with $f_c = 2.253$ GHz the beampipe cutoff frequency



$$\left(K - \lambda M + i\sqrt{\lambda} W^{\text{TEM}} + i\sqrt{\lambda - \kappa} W_{11}^{\text{TE}} \right) x = 0$$

Problem parameters:

- adaptive unstructured mesh with 2,877,955 quadratic tetrahedral elements
- second order basis functions
- total degrees of freedom $n = 17,273,664$

$$\left(K - \lambda M + i\sqrt{\lambda} W^{\text{TEM}} + i\sqrt{\lambda - \kappa} W_{11}^{\text{TE}} \right) x = 0$$

Problem parameters:

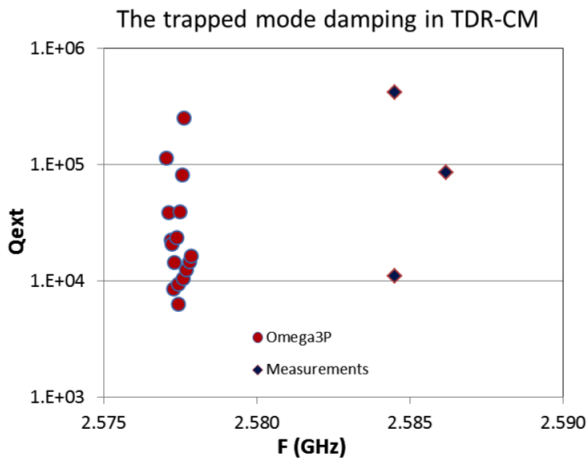
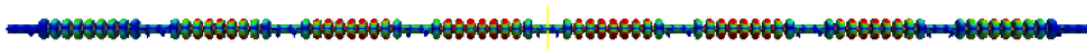
- adaptive unstructured mesh with 2,877,955 quadratic tetrahedral elements
- second order basis functions
- total degrees of freedom $n = 17,273,664$

Solution:

- 960 cores on NERSC Edison
- less than 10 minutes to compute 16 trapped modes

TESLA SRF cavity cryomodule (LCLS-II)

Electric field amplitude profile for the highest external Q mode

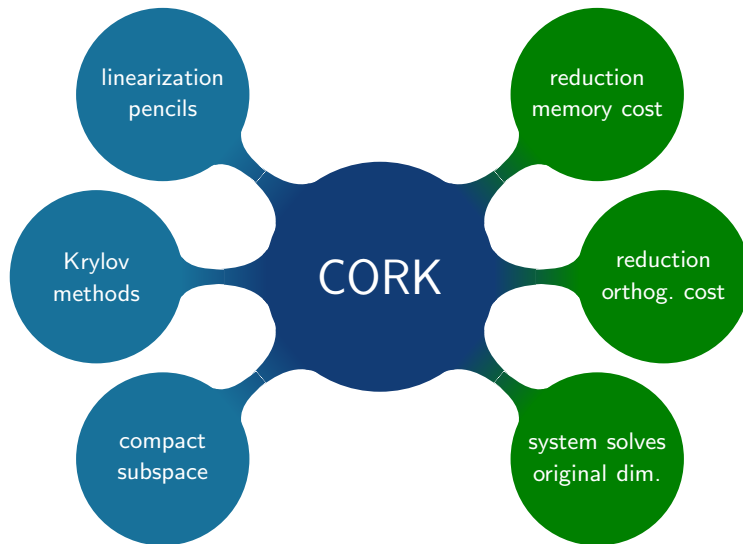


How to solve NLEP's

$$F(\lambda)x = 0$$

- 1 Approximation via interpolation
- 2 Linearization
- 3 Solve linear eigenvalue problem

Compact Rational Krylov (CORK) framework



- 1 **RVB**, O. MARQUES, E.G. NG, C. YANG, Z. BAI, L. GE, O. KONONENKO, Z. LI, C.-K. NG, L. XIAO

Computing resonant modes of accelerator cavities by solving nonlinear eigenvalue problems via rational approximation

Journal of Computational Physics, 374, 1031–1043, 2018

- 2 **RVB**, K. MEERBERGEN, AND W. MICHIELS

Compact rational Krylov methods for nonlinear eigenvalue problems

SIAM Journal on Matrix Analysis and Applications, 36(2), 820–838, 2015

CORK software available on my homepage:

<http://www.roelvanbeeumen.be>